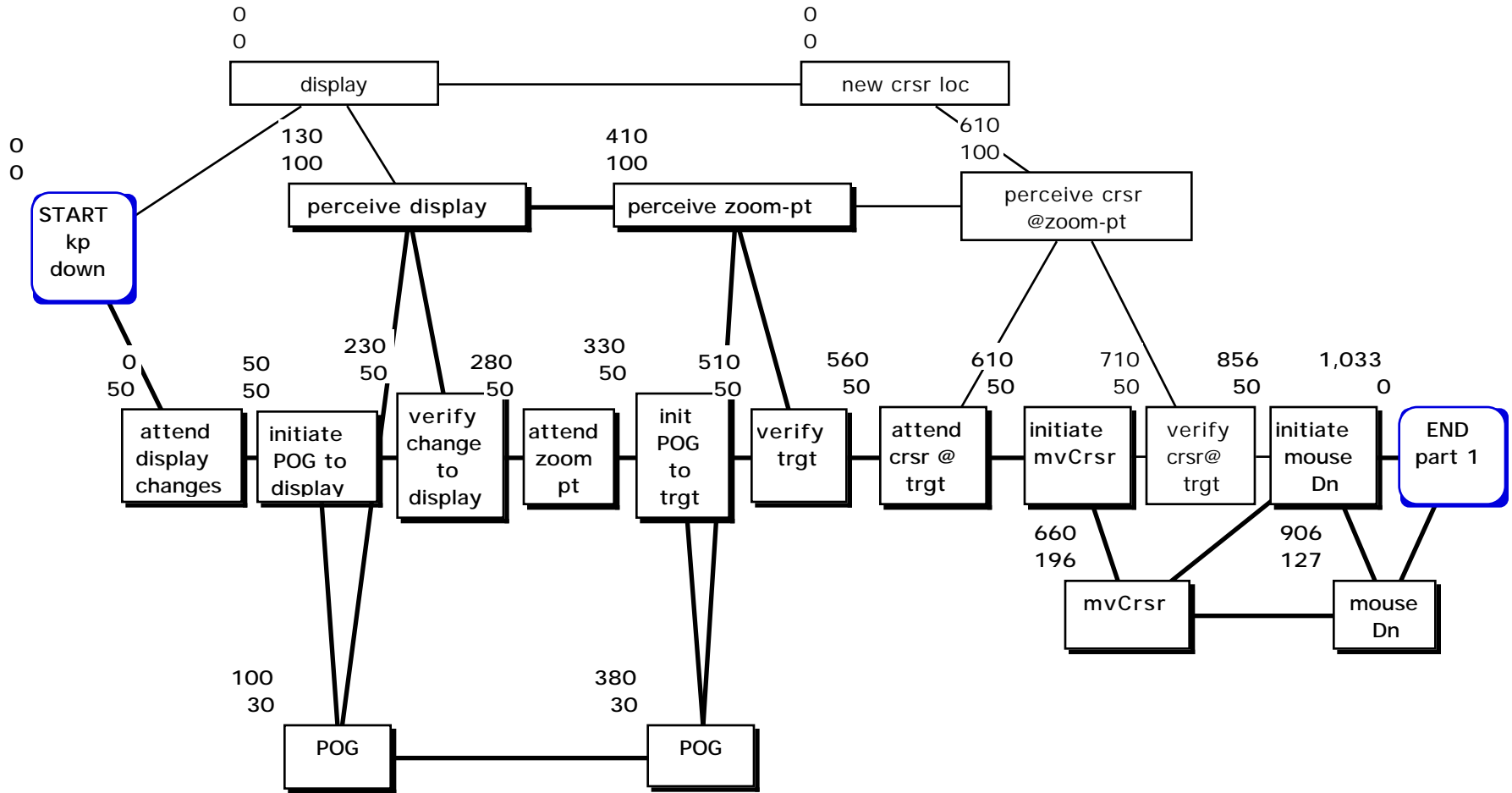


P1

Part 1 kp#3 to mDn@trgt-- slow microstrategy

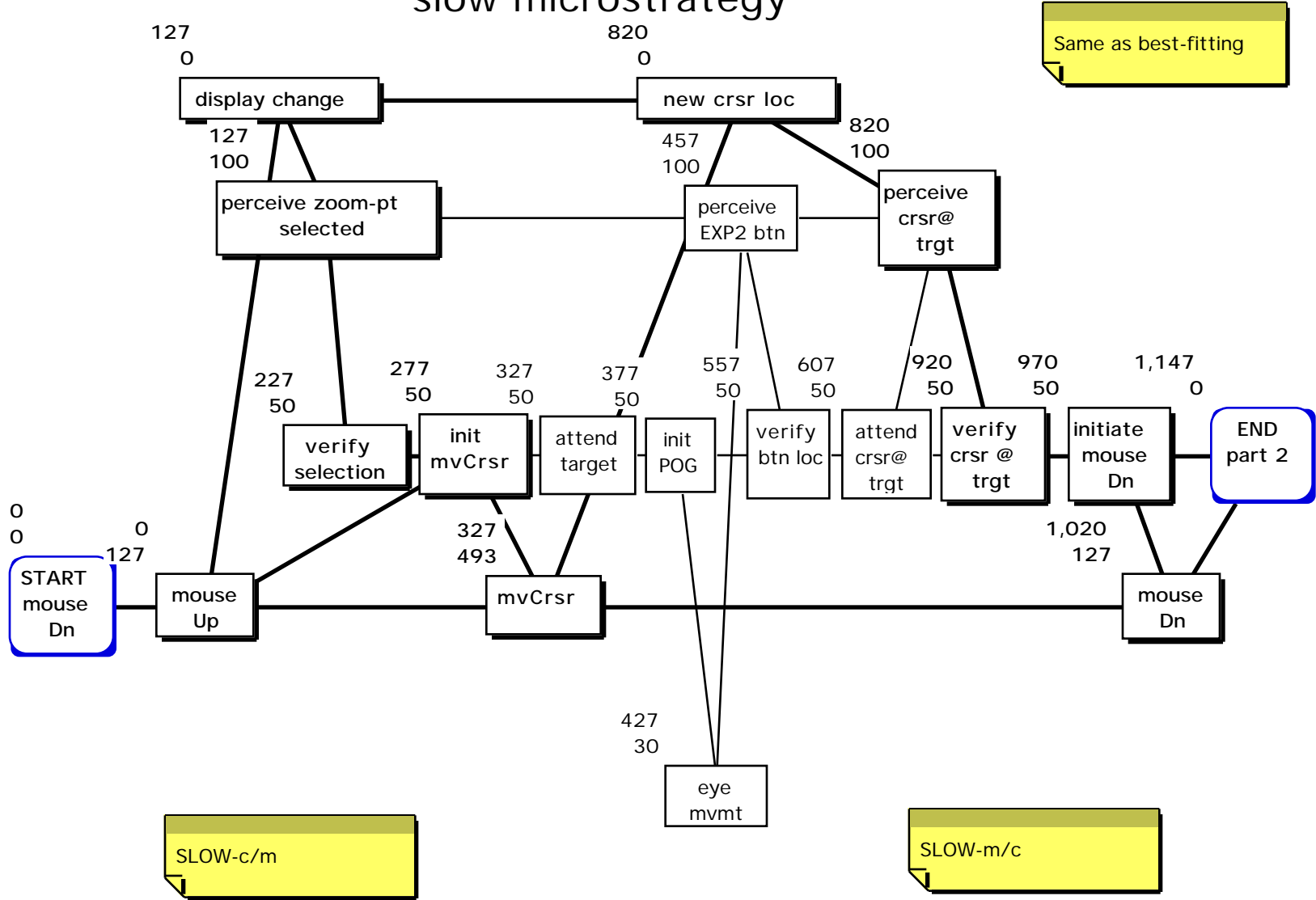


SLOW-kp/m: Combined with SLOW-m/c the "before" way

SLOW-m/c -- w/ POG to trgt prior to move (see notes in "activities & microstrategies" CPM-GOMS.

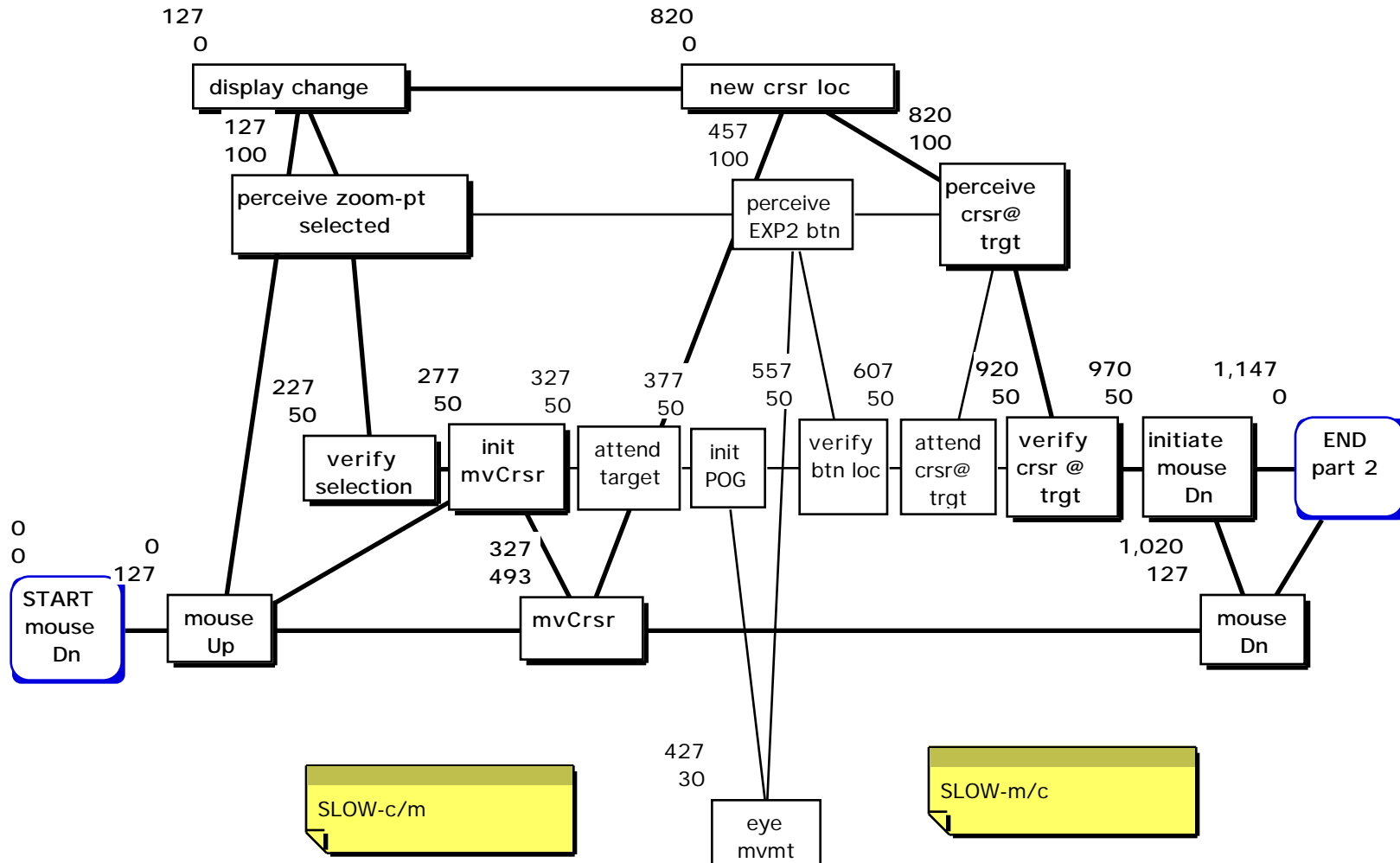
P1

Part 2 mDn@trgt to mDn@exp2 btn slow microstrategy



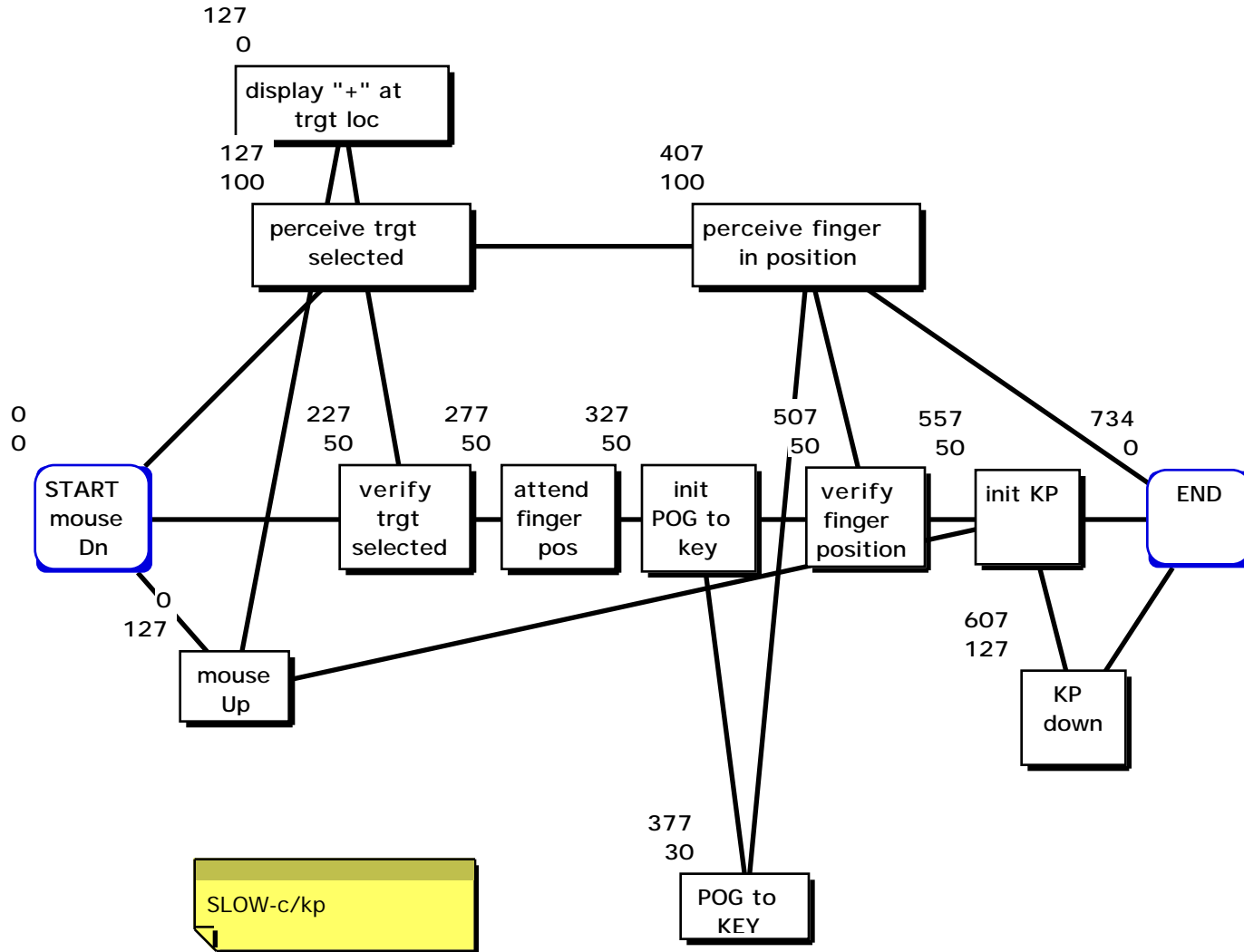
P1

Part 3 mDn@exp2 btn to mDn@way-point slow microstrategy



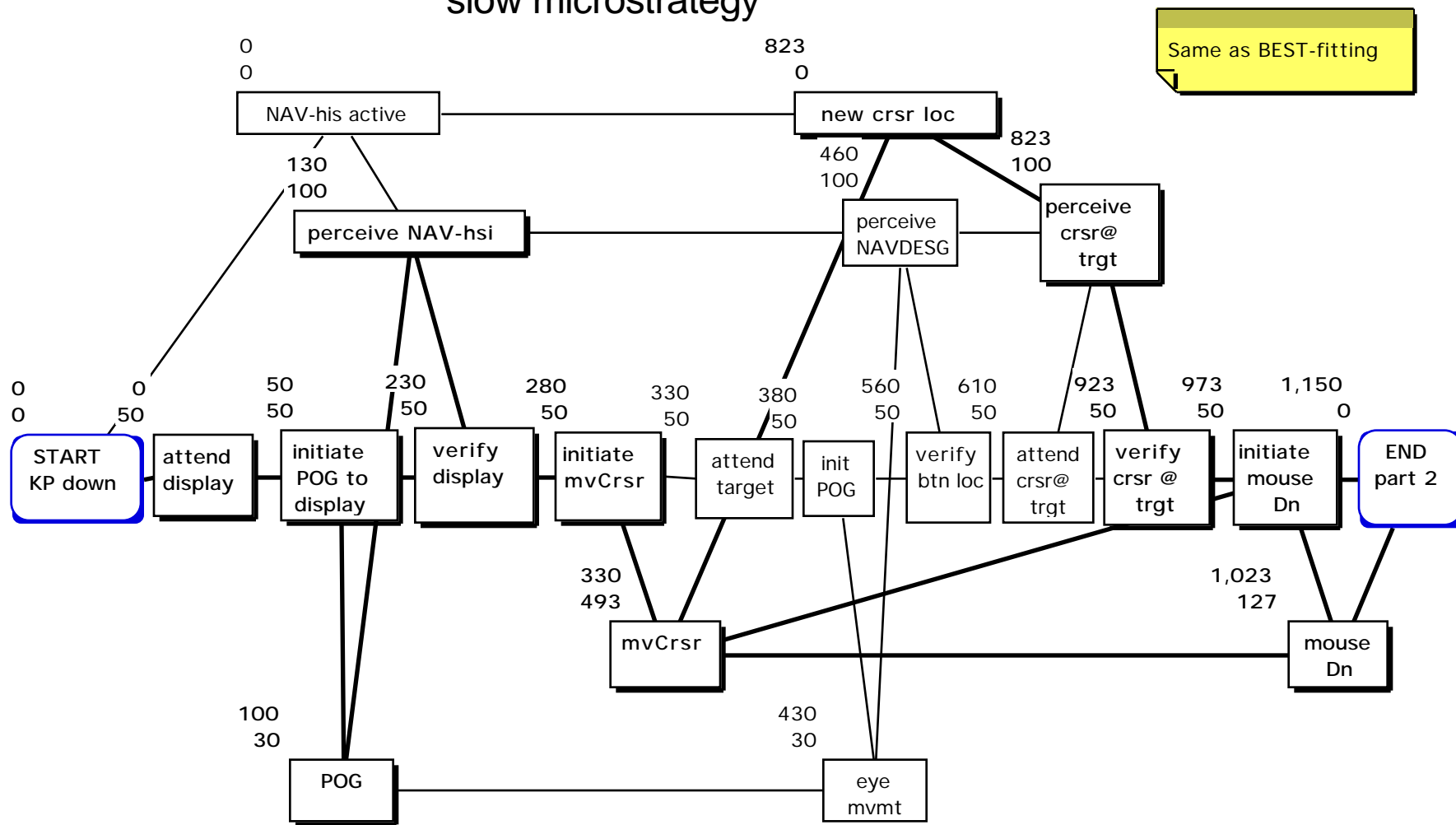
P1

Part 4 mDn@way-point to KP#2 slow microstrategy



P1

Part 5 KP#2 to mDn@NavDes slow microstrategy

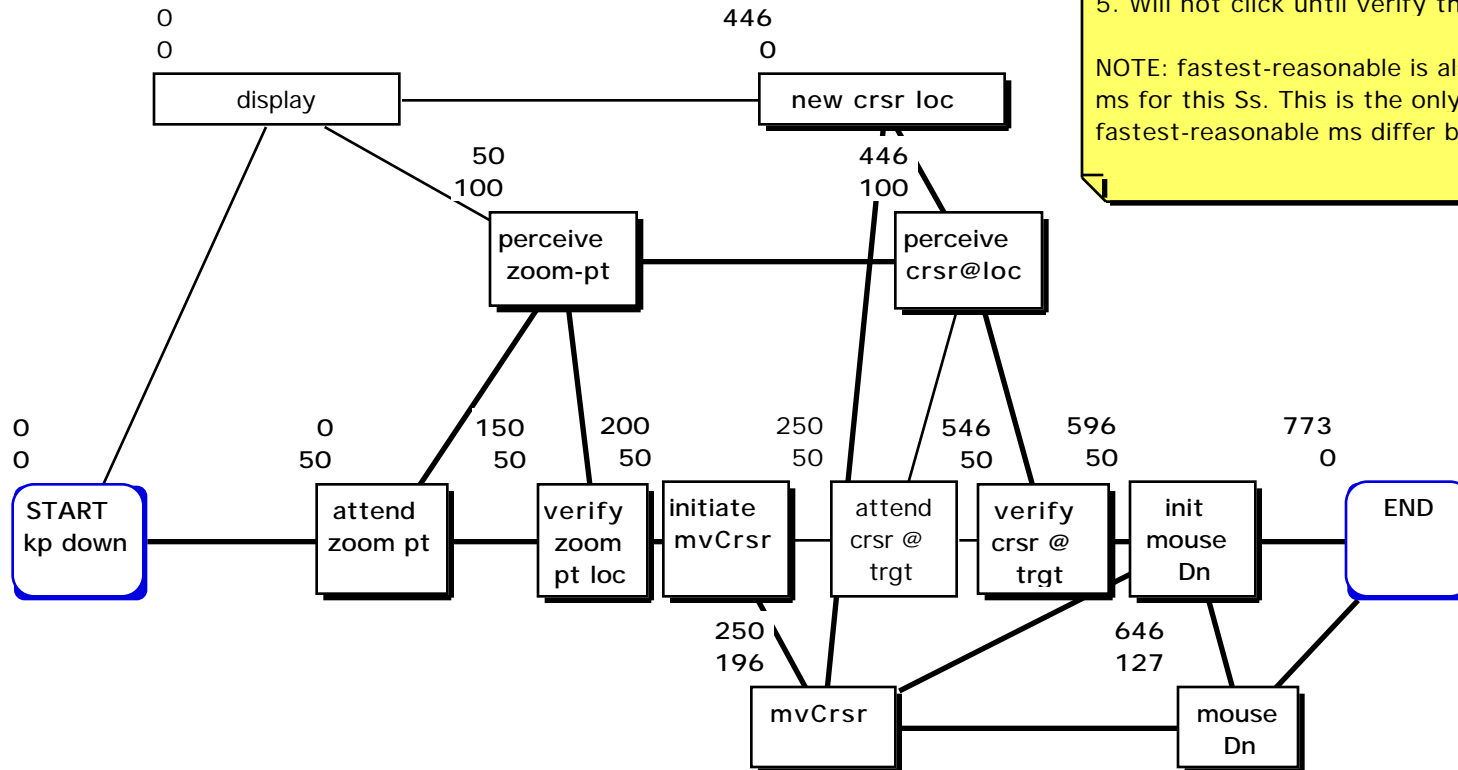


Same as BEST-fitting

SLOW-kp/m: There are three ways to join SLOW-kp/m with SLOW-m/c. This method is the AFTER way.

P1

Part 1 kp#3 to mDn@zoom-pt-- BEST-fitting microstrategy



1. This puts "mvCrsr" on the critical path. That is a very good thing.
2. Assumes that POG is fixed on center at time of kpDn.
3. "verify display active" is needed
4. another POG not needed to "perceive zoom pt" as zoom-pt is close to center.
5. Will not click until verify that crsr@loc.

NOTE: fastest-reasonable is also the best-fitting ms for this Ss. This is the only case in wh the fastest-reasonable ms differ bet. P1 and P2.

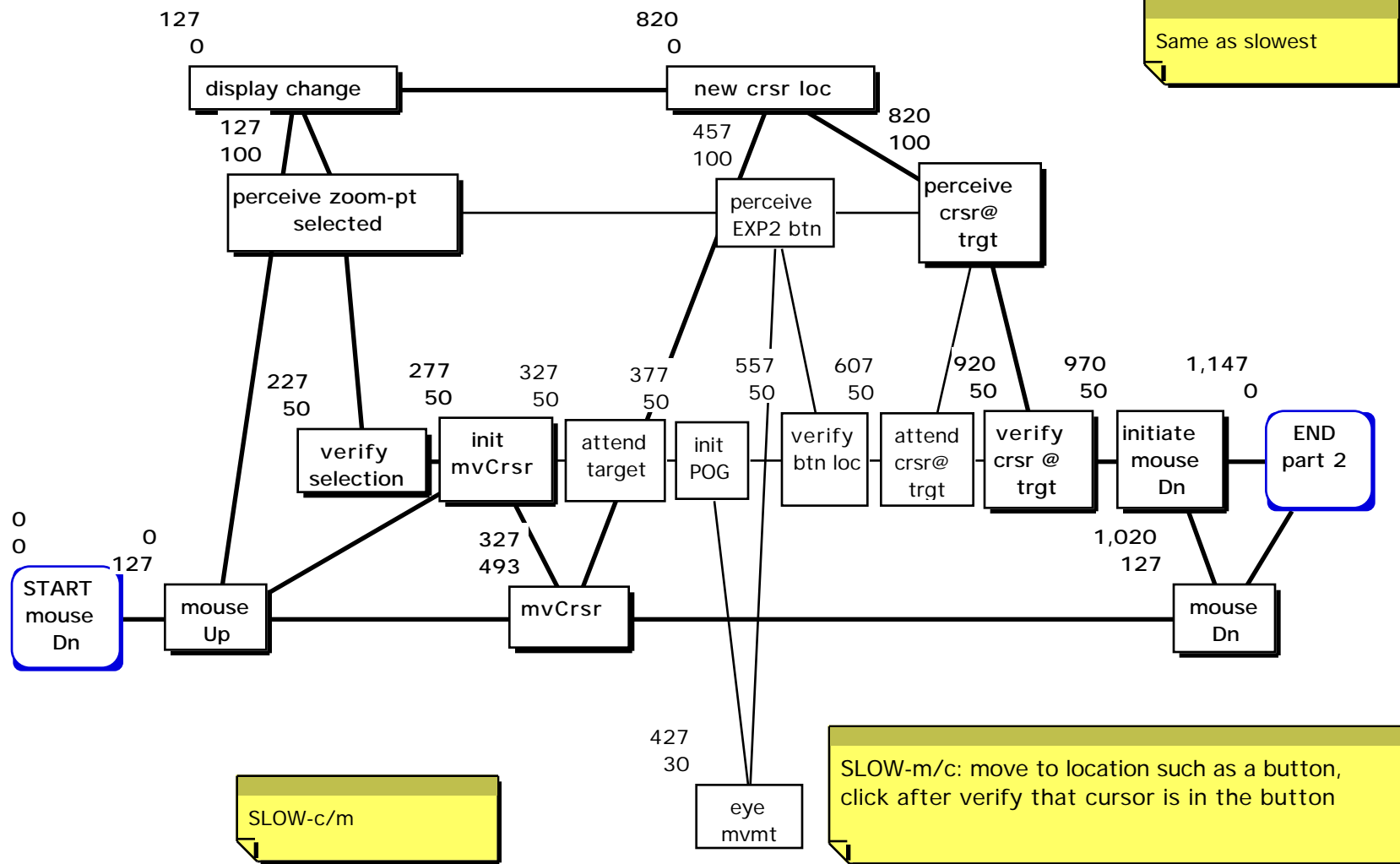
FAST-kp/m

SLOW-m/c: move to location such as a button,
click after verify that cursor is in the button

P1

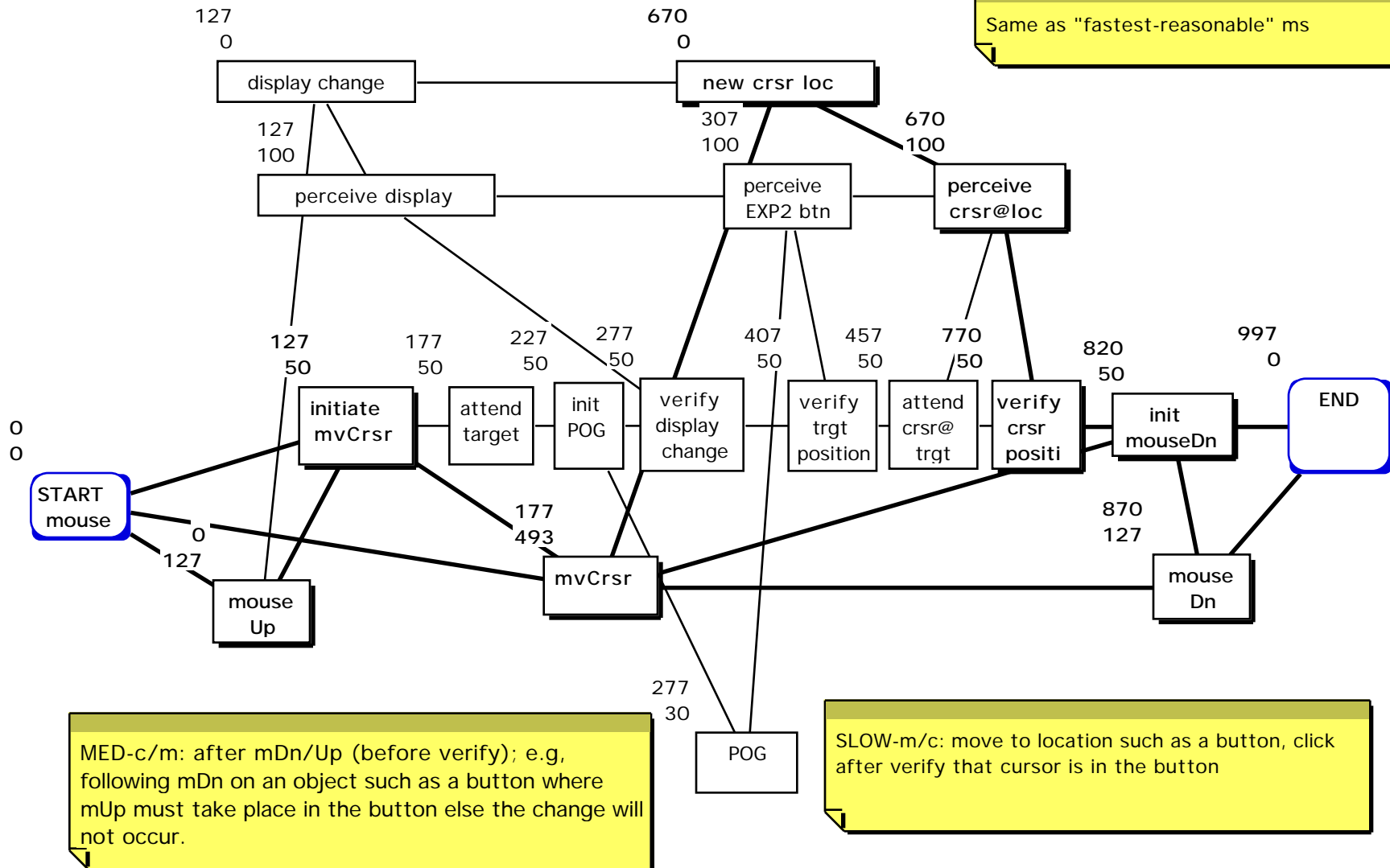
Part 2 mDn@zoom-pt to mDn@exp2 btn

BEST-fitting microstrategy



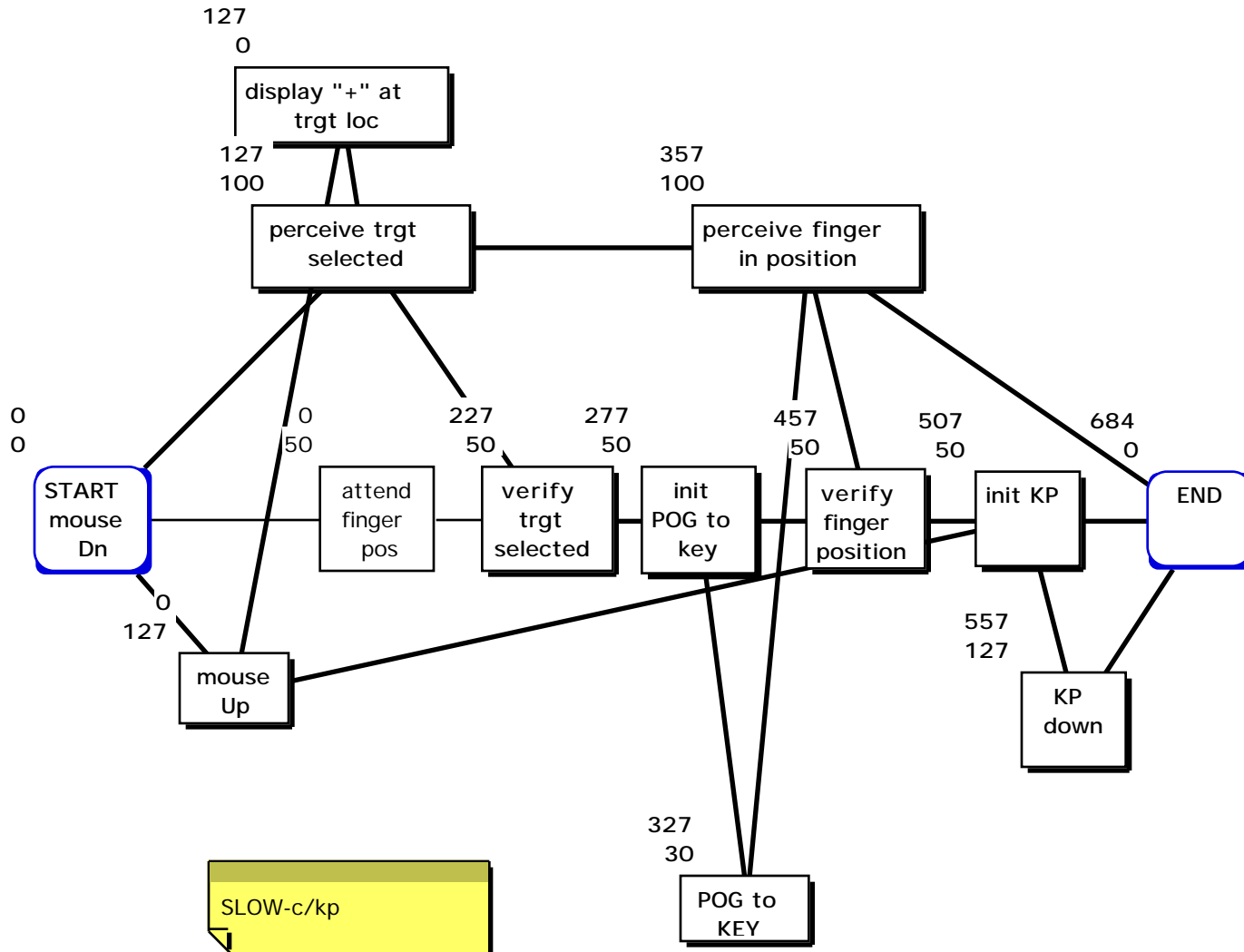
P1

Part 3 mDn@exp2 btn to mDn@way-point BEST-fitting microstrategy



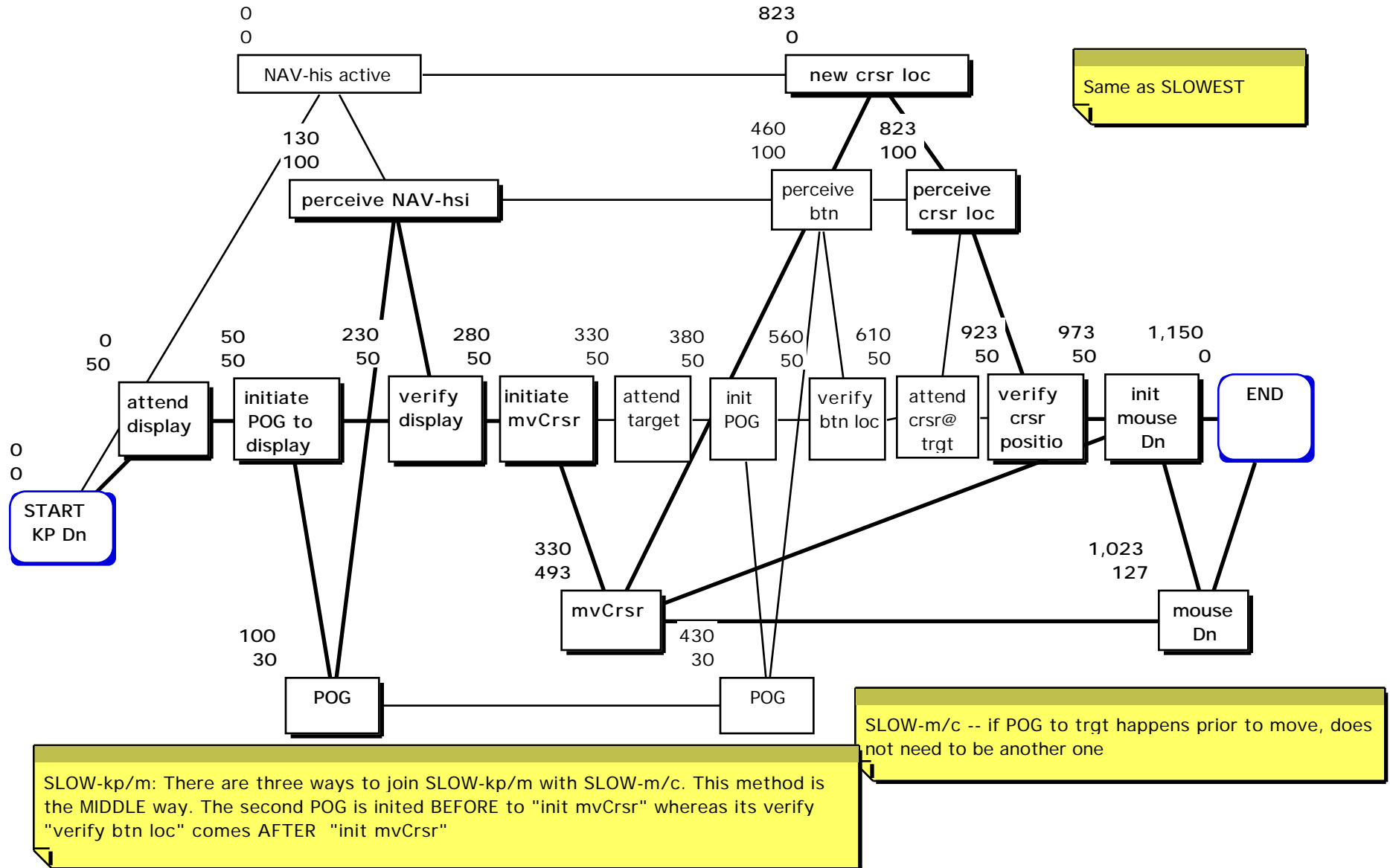
P1

Part 4 mDn@way-point to KP#2 BEST-fitting microstrategy



P1

Part 5 KP#2 to mDn@NavDes BEST-fitting microstrategy

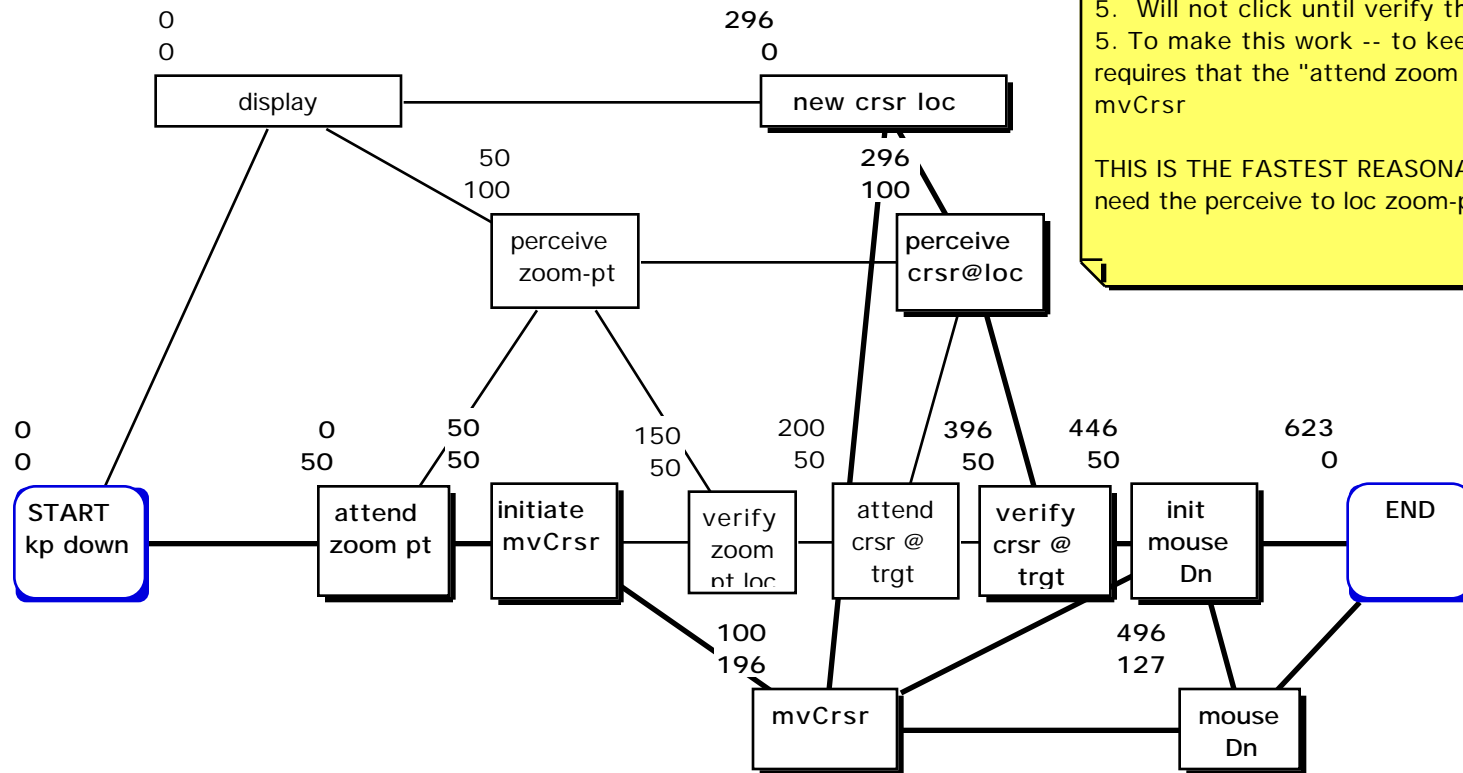


P1

Part 1 kp#3 to mDn@zoom-pt-- fastest-reasonable microstrategy

1. Assume that Ss knows that surface radar display will be infallibly selected by kp (verify not needed)
2. POG to center precedes kp#3; hence "init POG" etc not needed here. Just needs the "attend zoom pt."
3. Must "perceive zoom-pt"
4. This puts "mvCrsr" on the critical path. That is a very good thing.
5. Will not click until verify that crsr@loc.
5. To make this work -- to keep mvCrsr on CP -- requires that the "attend zoom pt" precede "init mvCrsr"

THIS IS THE FASTEST REASONABLE MODEL BECAUSE:
need the perceive to loc zoom-pt.

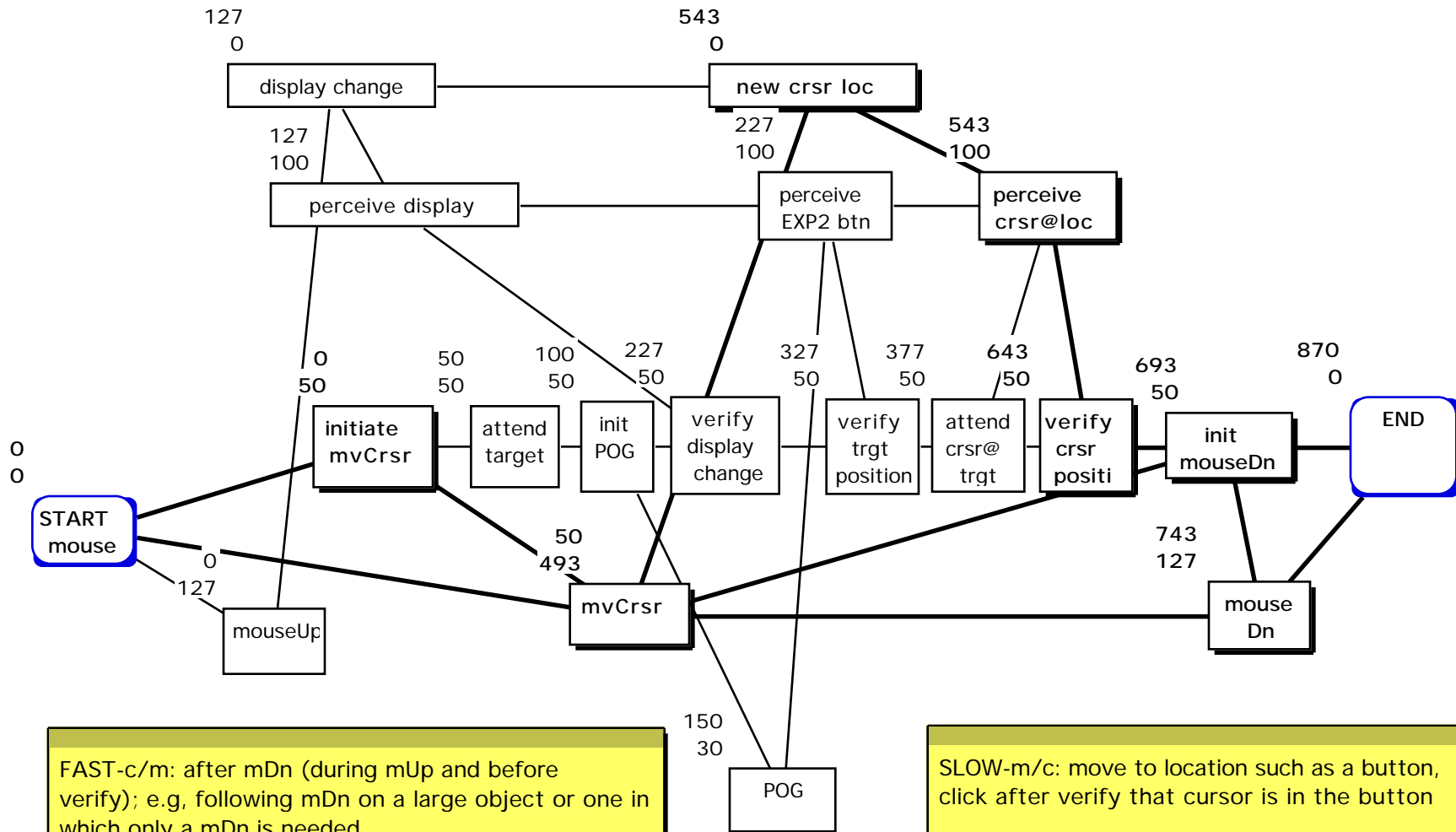


FAST-kp/m

SLOW-m/c: move to location such as a button,
click after verify that cursor is in the button

P1

Part 2 mDn@zoom-pt to mDn@exp2 btn
fastest-reasonable microstrategy

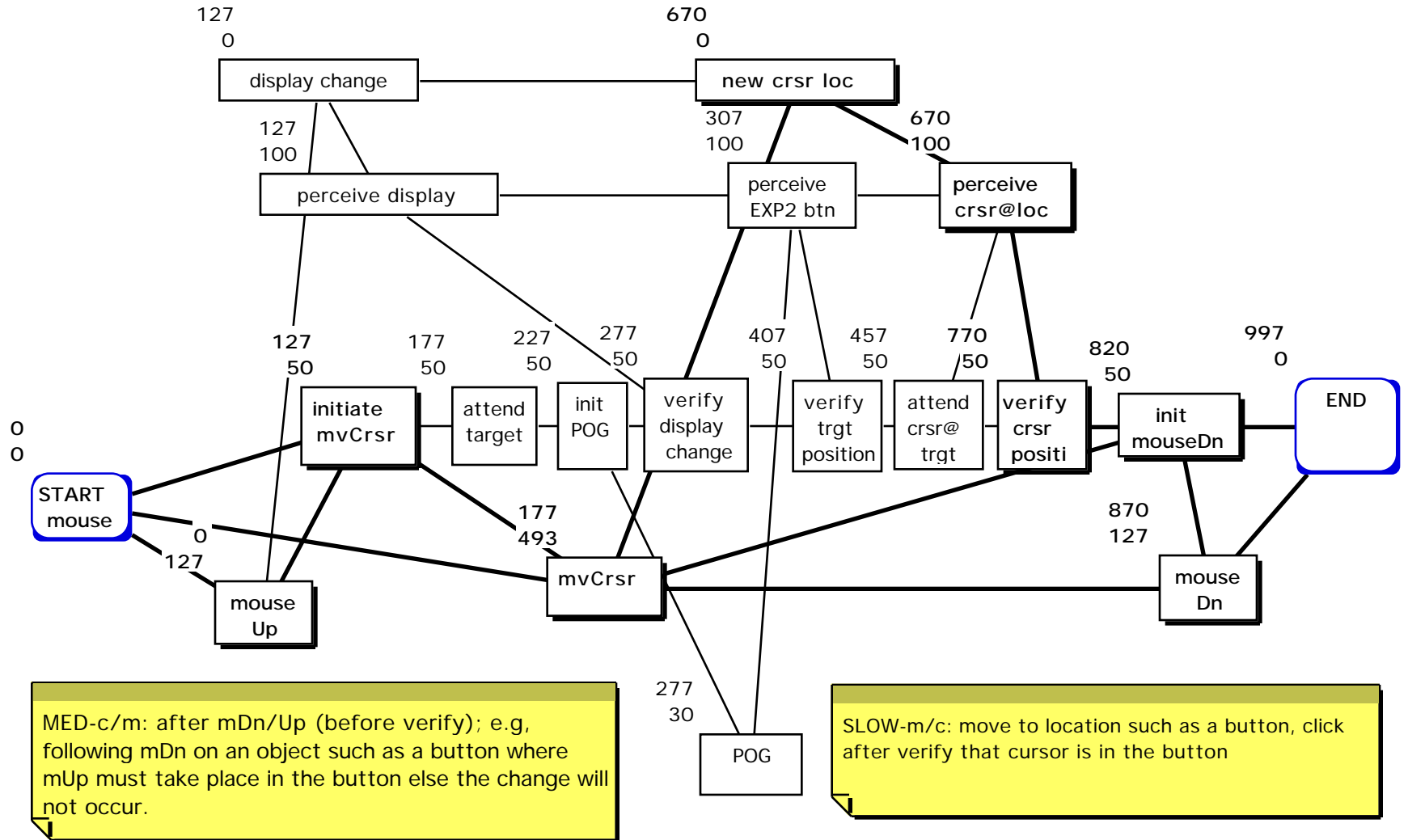


FAST-c/m: after mDn (during mUp and before verify); e.g, following mDn on a large object or one in which only a mDn is needed.

SLOW-m/c: move to location such as a button, click after verify that cursor is in the button

P1

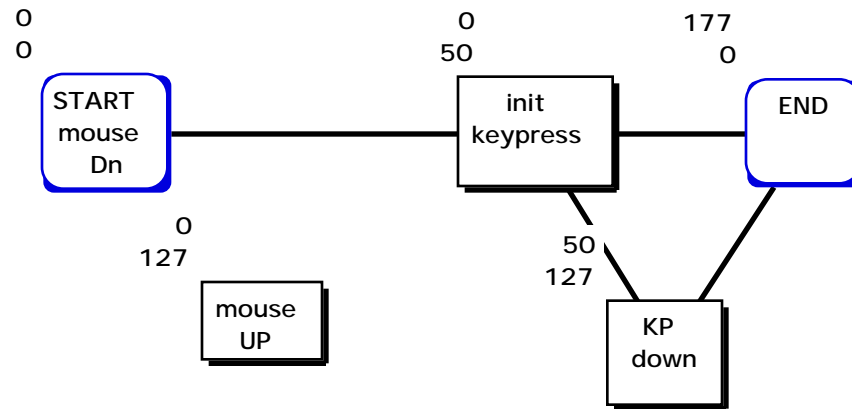
Part 3 mDn@exp2 btn to mDn@way-point fastest-reasonable microstrategy



P1

Part 4 mDn@way-point to KP#2

fastest-reasonable microstrategy



FAST-c/kp: this is the fastest.

P1

Part 5 KP#2 to mDn@NavDes
fastest-reasonable microstrategy

